Course Title	е	Robotics and Artificial Intelligence			ce in the second se	Course	Code	K	T370-371
Transcript Title: Robotics 1A/1B		Robotics and Art 1A/1B		Grades Levels:	11-12	Boa	rd Adop D	tion ate:	6/09/2020
Content Area: CTE			GPA Scale:	4.0	Date Course Submitted: 3/13/2		3/13/20		
Credential CTE / Si Required: IndusTe				Graduation Subject Areas:	Elective	tive CALPADS 7730		0	
UC/CSU "A-G" / Approvals:	Area		TBD		School Site/person that wrote and submitted the course:			CDM	
Recommend Skills:				al					
Next course(s):	Ca	Capstone course - TBD							
Textbook to be used:	Sc	Software and industry publications and scholarly articles.							

Course Title	Robo	otics and A	rtificial Intelliger	Course Code	KT370-371			
<b>Robotics and Artificial Intelligence</b>								
DATE:		March 6, 2020						
INDUSTRY SECTO	R:	Engineering & Architecture						
PATHWAY:		Engineering Design (152)						
CALPADS TITLE:		Intermedia	ate Engineering I	Design (Concentrato	r)			
CALPADS CODE: 7730								
HOURS:		Total Classroom Laboratory/CC/CVE						
	180 60 120							

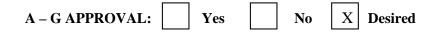
JOB TITLE	ONET CODES	JOB TITLE	ONET CODES
Electronics Engineering Technologist	17-3029.04	Mechatronics Engineers	17-2199.05
Robotics Technicians	17-3024.01		
Software Developers	15-1132.00		

### **COURSE DESCRIPTION:**

The Robotics and Artificial Intelligence (AI) course will introduce students to the growing field of mechatronics, advanced robotics systems and machine learning or artificial intelligence. Students will research and design "intelligent" robotic systems that solve real world problems by learning and refining their skills in mechanization and control, sensors, machine learning programming and data collection that leads to logic and predictive outcomes. Students will complete at least 4 mechatronic/robotics projects per school year, with their final project culminating in a presentation of how the machines will be used in real world scenarios.

### **PREREQUISITES:**

High School Name:	Site Prerequisite:
Corona del Mar High School	Principles of Engineering - 2 <sup>nd</sup> pathway course



Course Title	Robotics and	Artificial Intelligence	Course Code KT370-37			
ARTICULATION: TBD						
High School Name	e:	College Name:	<b>College Course Ti</b>	tle:		
LEVEL: Introductory X Concentrator Capstone						
High School Name:		Embedded/Leads to:	Description:			

## **METHOD OF STUDENT EVALUATION:**

- ✓ Pre and Post test
- ✓ Student Projects
- ✓ Written work
- ✓ Observation record of student performance
- ✓ Completion of assignments and assessments

### **METHOD OF INSTRUCTION:**

- ✓ Lecture and Discussion
- ✔ Group and individual applied projects
- $\checkmark$  Demonstration
- ✔ Field Trips
- ✔ Guest Speaker

### **RECOMMENDED TEXTS:**

No textbooks Industry Scholarly Articles Required software: **Canvas** to deliver the curriculum, **Anaconda** and **Arduino** for Python and C/C++ programming

Course TitleRobotics and Artificial IntelligenceCourse CodeKT370-371

### **MODEL CTE PATHWAY:**

Grade	Fall Semester	Spring Semester
9	Introduction to Design Engineering 1A	Introduction to Design Engineering 1B
10	Principles of Engineering 1A	Principles of Engineering 1B
11	Robotics and Artificial Intelligence 1A	Robotics and Artificial Intelligence 1B
12	Capstone – TBD, 21/22	Capstone – TBD, 21/22

### CALIFORNIA CAREER TECHNICAL EDUCATION MODEL CURRICULUM STANDARDS

California Department of Education CTE Standards website: <u>http://www.cde.ca.gov/ci/ct/sf/ctemcstandards.asp</u> Engineering and Architecture: <u>https://www.cde.ca.gov/ci/ct/sf/documents/enginearchit.pdf</u> Information and Communication Technologies: <u>https://www.cde.ca.gov/ci/ct/sf/documents/infocomtech.pdf</u>

### INDUSTRY SECTOR KNOWLEDGE AND PERFORMANCE ANCHOR STANDARDS

**1.0 Academics:** Analyze and apply appropriate academic standards required for successful industry sector pathway completion leading to postsecondary education and employment. Refer to the Engineering and Architecture and Information and Communication Technologies academic alignment matrix for identification of standards.

**2.0 Communications:** Acquire and accurately use Engineering and Architecture and Information and Communication Technologies sector terminology and protocols at the career and college readiness level for communicating effectively in oral, written, and multimedia formats. (Direct alignment with LS 9-10, 11-12.6)

2.1 Recognize the elements of communication using a sender–receiver model.

2.2 Identify barriers to accurate and appropriate communication.

2.3 Interpret verbal and nonverbal communications and respond appropriately.

2.4 Demonstrate elements of written and electronic communication such as accurate spelling, grammar, and format.

2.5 Communicate information and ideas effectively to multiple audiences using a variety of media and formats. 2.6 Advocate and practice safe, legal, and responsible use of digital media information and communications technologies.

2.7 Use technical writing and communication skills to work effectively with diverse groups of people.

2.8 Understand the principles of a customer-oriented service approach to users.

**3.0 Career Planning and Management:** Integrate multiple sources of career information from diverse formats to make informed career decisions, solve problems, and manage personal career plans. (Direct alignment with SLS 11-12.2) 3.1 Identify personal interests, aptitudes, information, and skills necessary for informed career decision making. 3.2 Evaluate personal character traits such as trust, respect, and responsibility and understand the impact they can have on career success. 3.3 Explore how information and communication technologies are used in career planning and decision making. 3.4 Research the scope of career opportunities available and the requirements for education, training, certification, and licensure. 3.5 Integrate changing employment trends, societal needs, and economic conditions into career planning. 3.6 Recognize the role and function of professional organizations, industry associations, and organized labor in a productive society.

3.7 Recognize the importance of small business in the California and global economies.

3.8 Understand how digital media are used by potential employers and postsecondary agencies to evaluate candidates. 3.9 Develop a career plan that reflects career interests, pathways, and postsecondary options.

Course Title	Robotics and Artificial Intelligence	Course Code	KT370-371					
	se existing and emerging technology to investigate, r							
	nation, as required in the Engineering and Architectu		munication					
	workplace environments. (Direct alignment with WS							
	eference materials to gather information and produce							
	by based communications responsibly and effectivel							
	and communication technologies to synthesize, summ	narize, compare, and contras	st information from					
multiple sources.		-1						
associated sources.	4.4 Discern the quality and value of information collected using digital technologies, and recognize bias and intent of the							
	resent, and projected technological advances as they i	mpact a particular pathway						
	of various information and communication technolog		ent nonulations as nart					
	rrent literature or in relation to the information task.	gies to interact with constitut	ent populations as part					
of a search of the ca	from merature of in relation to the information task.							
5.0 Problem Solving	g and Critical Thinking: Conduct short, as well as	more sustained, research to c	create alternative					
	a question or solve a problem unique to the Engineeri							
	hnologies sectors using critical and creative thinking,							
	(Direct alignment with WS 11-12.7)		1 57 1					
	significant questions that clarify various points of vie	ew to solve problems.						
5.2 Solve predictable	e and unpredictable work-related problems using vari	ous types of reasoning (indu	ctive, deductive) as					
appropriate.								
	king to analyze how various components interact wit	h each other to produce outc	comes in a complex					
work environment.								
	ation and draw conclusions, based on the best analysis							
	d structured approach to isolate and identify the source	e of problems and to resolve	problems. 5.6 Know					
	es for identifying and resolving problems.							
	ms iteratively and recursively.							
	lgorithms and solve problems.							
5.10 Use multiple la	e problems into components to solve.							
1 .	concept of base systems, including binary and hexad	acimal						
	epts of Boolean logic to decision making and searching							
5.12 Apply the cone	epis of boolean logic to decision making and searching	ng.						
6.0 Health and Safe	ety: Demonstrate health and safety procedures, regul	ations, and personal health p	ractices and determine					
	pols, key terms, and domain-specific words and phras							
0	Communication Technologies sector workplace envi		0					
12.4)	0	Č.						
6.1 Locate, and adhe	ere to, Material Safety Data Sheet (MSDS) instruction	18.						
6.2 Interpret policies	s, procedures, and regulations for the workplace envir	conment, including employer	and employee					
responsibilities.								
	afety practices for storing, cleaning, and maintaining	tools, equipment, and suppli	es. 6.4 Practice personal					
2 U	bending, or moving equipment and supplies.							
	l safety when lifting, bending, or moving equipment a							
	w to prevent and respond to work-related accidents or	injuries; this includes demo	nstrating an					
understanding of erg								
	and healthful working environment.		<b>`</b>					
o. / Be informed of l	aws/acts pertaining to the Occupational Safety and H	eaith Administration (OSHA	<b>\</b> <i>)</i> .					

6.8 Maintain a safe and healthful working environment.

6.9 Dispose of e-waste properly, understanding the health, environmental, and legal risks of improper disposal. 6.10 Act

Course Title Robotics and Artificial Intelligence	Course Code	KT370-371
---	-------------	-----------

conscientiously regarding the use of natural resources (e.g., paper, ink, etc.)

6.11 Conserve energy while computing (e.g., turn off equipment at night, power-saving settings, etc.)

**7.0 Responsibility and Flexibility:** Initiate, and participate in, a range of collaborations demonstrating behaviors that reflect personal and professional responsibility, flexibility, and respect in the Engineering and Architecture and Information and Communication Technologies sector workplace environments and community settings. (Direct alignment with SLS 9-10, 11-12.1)

7.1 Recognize how financial management impacts the economy, workforce, and community.

7.2 Explain the importance of accountability and responsibility in fulfilling personal, community, and workplace roles.

7.3 Understand the need to adapt to changing and varied roles and responsibilities.

7.4 Practice time management and efficiency to fulfill responsibilities.

7.5 Apply high-quality techniques to product or presentation design and development.

7.6 Demonstrate knowledge and practice of responsible financial management.

7.7 Demonstrate the qualities and behaviors that constitute a positive and professional work demeanor, including appropriate attire for the profession.

7.8 Explore issues of global significance and document the impact on the Engineering and Architecture and Information and Communication Technologies sectors.

**8.0 Ethics and Legal Responsibilities:** Practice professional, ethical, and legal behavior, responding thoughtfully to diverse perspectives and resolving contradictions when possible, consistent with applicable laws, regulations, and organizational norms. (Direct alignment with SLS 11-12.1d)

8.1 Access, analyze, and implement quality assurance standards of practice.

8.2 Identify local, district, state, and federal regulatory agencies, entities, laws, and regulations related to the Engineering and Architecture and Information and Communication Technologies industry sectors.

8.3 Demonstrate ethical and legal practices consistent with Information and Communication

Technologies sector workplace standards.

8.4 Explain the importance of personal integrity, confidentiality, and ethical behavior in the workplace.

8.5 Analyze organizational culture and practices within the workplace environment.

8.6 Adhere to copyright and intellectual property laws and regulations, and use and appropriately cite proprietary information.

8.7 Conform to rules and regulations regarding sharing of confidential information, as determined by Engineering and

Architecture and Information and Communication Technologies sector laws and practices.

8.8 Identify legal and ethical issues that have proliferated with increased technology adoption, including hacking, scamming, and breach of privacy.

**9.0 Leadership and Teamwork:** Work with peers to promote divergent and creative perspectives, effective leadership, group dynamics, team and individual decision making, benefits of workforce diversity, and conflict resolution such as those practiced in the Future Business Leaders of America and SkillsUSA career technical student organization. (Direct alignment with SLS 11-12.1b)

9.1 Define leadership and identify the responsibilities, competencies, and behaviors of successful leaders.

9.2 Identify the characteristics of successful teams, including leadership, cooperation, collaboration, and effective decisionmaking skills as applied in groups, teams and career technical student organization activities.

9.3 Understand the characteristics and benefits of teamwork, leadership, and citizenship in the school, community, and workplace setting.

9.4 Explain how professional associations and organizations and associated leadership development and competitive career development activities enhance academic preparation, promote career choices, and contribute to employment opportunities. 9.5 Understand that the modern world is an international community and requires an expanded global view.

9.6 Respect individual and cultural differences and recognize the importance of diversity in the workplace.

9.7 Participate in interactive teamwork to solve real Engineering and Architecture and Information and Communication Technologies sector issues and problems.

**10.0 Technical Knowledge and Skills:** Apply essential technical knowledge and skills common to all pathways in the Engineering and Architecture and Information and Communication Technologies sectors, following procedures when carrying out experiments or performing technical tasks.(Direct alignment with WS 11-12.6)

10.1 Interpret and explain terminology and practices specific to the Engineering and Architecture and Information and Communication Technologies sectors.

10.2 Comply with the rules, regulations, and expectations of all aspects of the Engineering and Architecture and Information and Communication Technologies sectors.

10.3 Construct projects and products specific to the Engineering and Architecture and Information Communication Technologies sector requirements and expectations.

10.4 Collaborate with industry experts for specific technical knowledge and skills.

10.5 Understand the major software and hardware components of a computer and a network and how they relate to each other.

10.6 Understand data sizes of various types of information (text, pictures, sound, video, etc.) and data capacity of various forms of media.

10.7 Understand the SI (metric) prefixes commonly used in computing including, at least, kilo, mega, giga, and tera.

10.8 Understand security concepts including authorization, rights, and encryption.

10.9 Use common industry-standard software and their applications including word processing, spreadsheets, databases, and multimedia software.

10.10 Manage files in a hierarchical system.

10.11 Know multiple ways in which to transfer information and resources (e.g., text, data, sound, video, still images) between software programs and systems.

10.12 Know appropriate search procedures for different types of information, sources, and queries.

10.13 Evaluate the accuracy, relevance, and comprehensiveness of retrieved information.

10.14 Analyze the effectiveness of online information resources to support collaborative tasks, research, publications, communications, and increased productivity.

**11.0 Demonstration and Application:** Demonstrate and apply the knowledge and skills contained in the Engineering and Architecture and Information and Communication Technologies anchor standards, pathway standards, and performance indicators in classroom, laboratory, and workplace settings, and through career technical student organizations such as Future Business Leaders of America and SkillsUSA.

11.1 Utilize work-based/workplace learning experiences to demonstrate and expand upon knowledge and skills gained during classroom instruction and laboratory practices specific to the Engineering and Architecture and Information and Communication Technologies sector program of study.

11.2 Demonstrate proficiency in a career technical pathway that leads to certification, licensure, and/or continued learning at the postsecondary level.

11.3 Demonstrate entrepreneurship skills and knowledge of self-employment options and innovative ventures. 11.4 Employ entrepreneurial practices and behaviors appropriate to Engineering and Architecture and Information and Communication Technologies sector opportunities.

11.5 Create a portfolio, or similar collection of work, that offers evidence through assessment and evaluation of skills and knowledge competency as contained in the anchor standards, pathway standards, and performance indicators.

Cours	se Title Robotics and	Artificial Intelligence	Course C	ode KT370-371
CP = Classes	om LAB/CC = Laboratory/Shop/Comm	nunity Classroom		
$\frac{CR = Classro}{I}$	Introduction to Mechatronics Computing		LAB/ CC	STANDARDS
	<ul> <li>A. Why this class?</li> <li>Mechatronics systems a</li> <li>Bridging physical hardicomputational framework</li> <li>Overview of modern set</li> <li>Artificial Intelligence (</li> <li>B. Team Project #1: Design a mpaper and articulate its impact, psafety/ethics considerations. Sphardware, computational framework</li> <li>C. Syllabus and Classroom Exp</li> </ul>	2 ware with 2 orks or coding ensor technology (AI) in mechatronics mechatronics system on pros and cons, and ecify the physical work, sensor rolved in your system.	4	Academic: HS-PS3-3, HS-ETS1-1, N-Q.A, A-CED.A, G-CO.B, S-ID.C RLST 11-12.7, RLST 11-12.10,PE-12.6, US11.11 CTE Anchor: 1.0, 2.0, 4.0, 5.0, 6.0, 7.0, 8.0, 9.0, 10.0
II.	Physical Computing 1: Using Operators in Python + LocoA		LAB/ CC	CTE Pathway: B6.0 B9.0 B8.0 B.10 STANDARDS
	<ul> <li>A. Robotic Manipulators: Stude the anatomy of robotic manipulation</li> <li>Physical Construction</li> <li>Degrees of Freedom</li> <li>Sensorization</li> <li>Motor Technologies</li> <li>Python programming to LocoArm joints</li> </ul>	ators (arms) 4	8	Academic: HS-PS3-3, HS-ETS1-1, N-Q.A, A-CED.A, G-CO.B, S-ID.C N-VM6-10 CTE Anchor: 2.0, 4.0, 5.0, 6.0, 7.0, 8.0, 9.0, 10.0

Course Title	Robotics and Artificial Intelligence	Course	Course Code KT370				
	I. Physical Computing 2: Perform Input and Output Operations in Python + LocoArm Mapped Mode				LAB/ CC	STANDARDS	
B. Stud code at C. Teat	<ul> <li>omation and Controls: Students will explore control methods using the LocoArm Basic Control Mapped Bounds Path Planning Gripper Control</li> <li>ents will start using Python functionalities to tomated arm behavior Python Input and String Manipulation Module Imports Python Built-in Functions</li> <li>n Project #2: Gripper calibration and LocoArm allenge.</li> <li>Students will have to design different mapping algorithms and path planning techniques to get the LocoArm in particular poses.</li> <li>Students will employ an engineering design process to solve the pose challenge.</li> <li>O Design a step-by-step path-planning algorithm</li> <li>O Code and Test</li> <li>Evaluate Solution</li> </ul>	7	14	HS-N-Q S-II 2.0, 8.0,	0		

Cours	e Title Robotics and Artificial Intelli	igence	Course C	Code KT370-371
IV.	Physical Computing 3: Control Flow with Decisions and Loops in Python + LocoArm Mapped Mode	CR	LAB/ CC	STANDARDS
	<ul> <li>A. Students will explore loops and conditionals Python by creating data-driven LocoArm Behav.</li> <li>Loops and conditionals with LocoArm</li> <li>B. Team Project #3: LocoArm Pick-and-Place challenge.</li> <li>Students will synthesize all physical computing concepts covered so far to design, code, and test pick-and-place automation system.</li> <li>Students will account for LocoArm's ph and geometry to identify feasible path- planning and speed control parameters f successful pick-and-place operation.</li> <li>They will code the operation in Python repeatedly.</li> <li>They will perform basic statistics to qua errors in the operation.</li> <li>Student reflection: Students individually write a reflective essay covering what th enjoyed, challenges they overcame, and they learned about themselves through t pick-and-place challenge.</li> </ul>	ior 8 8 a hysics for a to test ntify what	14	Academic: HS-PS3-3, HS-ETS1-2 HS-ETS1-3, N-Q.A A-CED.A, A-REI.A, S- ID.A G-MG3, G-SRT1A-1B N-Q1-3, N-VM1-3, S- ID1-6a-c, SEP1-8, CC1-7, PS2A-C, PS3A-, ETS1A-C, ETS2A-B CTE Anchor: 2.0, 4.0, 5.0, 6.0, 7.0, 8.0, 9.0, 10.0 CTE Pathway: B6.0 B8.0 B10.0

Cours	e Title Robotics and Artificial Intelligence	,	Course	<b>Code</b> <i>KT</i> 370-371
V.	Physical Computing 4: Functions and visualizations in Python + LocoArm Mapped Mode	CR	LAB/ CC	STANDARDS
	<ul> <li>A. Students will practice writing custom Python functions for LocoArm automation.</li> <li>Custom Python Functions</li> <li>Variable Scope</li> <li>B. Students will use LocoArm's sensors and solar cell to understand the dependence of the power output to ambient conditions.</li> <li>Temperature Sensor Introduction</li> <li>Light Sensor Introduction</li> <li>Solar Cell Introduction</li> </ul>	5	10	Academic: HS-PS3-3, HS-ETS1-2 HS-ETS1-3, N-Q.A A-CED.A, A-REI.A S-ID.A, S-IC.B, SEP1- 8, CC1-7, PS2A-C, PS3A-, ETS1A-C, ETS2A-B CTE Anchor: 2.0, 4.0, 5.0, 6.0, 7.0, 8.0, 9.0, 10.0 CTE Pathway: B6.0 B8.0 B.10
VI.	Advanced Robotics 1: LocoArm Spherical Mode	CR	LAB/ CC	STANDARDS
	<ul> <li>A. Students will study advanced robotics concepts by reimagining the 3D space in which robots and humans operate.</li> <li>Cartesian and Spherical representation of the 3D workspace of LocoArm</li> <li>B. Students will study advanced path planning algorithms and Python techniques to implement these planning algorithms.</li> <li>Object manipulation algorithms</li> <li>Point Grids</li> <li>File Output (Saving Data to Files)</li> <li>File Input (Loading Data from Files)</li> <li>Calibration and Override</li> </ul> C. Team Project #4: Advanced path-planning algorithm for sensor-based decision making. <ul> <li>Students will use the engineering design process to perform temperature and light sweeps to create a 2D map of optimal grid points for maximum solar power generation. <ul> <li>Students will demonstrate their solutions for the class.</li> </ul></li></ul>	6	12	Academic: HS-PS3-3, HS-ETS1-2, N- Q.A, A-CED.A, A-REI.A, G- GMD.B, S-ID.A, S-IC.B, S- ID.C,SEP1-8, CC1-7, PS2A- C, PS3A-, ETS1A-C, ETS2A-, PE-12.6, US11.11 CTE Anchor: 2.0, 4.0, 5.0, 6.0, 7.0, 8.0, 9.0, 10.0 CTE Pathway: B6.0 B9.0 B8.0 B.10

Cours	se Title Robotics and Artificial Intelligence		Course	Code	KT370-371
VII	Sensor Technology 1: LocoIoT Inputs and Outputs with Product Design	CR	LAB/ CC		STANDARDS
	<ul> <li>A. Students will dive into modern sensors that power advanced robotics systems.</li> <li>Technical challenges of sensor selection</li> <li>Sensor errors</li> <li>Input sensors</li> <li>B. Students will use Python code to study real-time sensor data analytics. They will write Python code to</li> <li>Acquire raw sensor data</li> <li>Transform data in a usable form</li> <li>Analyze data using basic statistics</li> <li>Visualize results using charts and graphical tools</li> <li>C. Students will explore modern output devices that make human-robot interaction feasible in a safe and ethical manner.</li> <li>D. Team Project #5: Real world product development 1: Students will design and prototype a product that solves a real-world need. Specifically, they will follow the following engineering and product design steps:</li> <li>Identify and define a real-world problem that needs to be solved</li> <li>Generate solution concepts using sensors and outputs</li> <li>Design sensor data analytics based decisionmaking algorithm</li> <li>Code and Test</li> <li>Evaluate Solution</li> </ul>	8	16	HS-PS3 ETS1-2 N-Q.A, S-ID.A, CC1-7, ETS1A 12.6, U 2.0, 8.0	ademic: 3-3, HS-ETS1-1, HS- , HS-ETS1-3 A-CED.A, A-REI.A , S-IC.B,SEP1-8, PS2A-C, PS3A-, -C, ETS2A-B, PE- S11.11 E Anchor: , 4.0, 5.0, 6.0, 7.0, , 9.0, 10.0 E Pathway: 0 0 0

Cours	ourse Title Robotics and Artificial Intelligence		Course	Code	KT370-371
VIII.	Advanced Robotics 2: LocoIoT Internet Connected Systems Cloud Robotics	CR	LAB/CC		STANDARDS
	<ul> <li>A. Students will study modern cloud technology history and outlook.</li> <li>B. Students will learn how to code a local server that can transfer sensor data to a webpage via the internet.</li> <li>C. Students will learn how to host this server on Amazon Web Services (AWS) cloud platform and build a dashboard to visualize sensor data.</li> <li>D. Team Project #6: Real-world product development 2: Students will build on their previous product design from Unit VII. to design a webpage that is hosted in the cloud. This webpage will provide a user-friendly dashboard to the customer showing real-time sensor data behavior and the ability for users to affect the product state remotely.</li> <li>Students will edit their earlier Kickstarter/Crowdsorucing type marketing video to showcase the dashboard and user interface of their product and share it with everyone in the class.</li> </ul>	8	16	H 1, ETS1-3 N A S 7, PS2A C, ETS US11.1 CT 2.0 8.0	I-Q.A,A-CED.A, I-REI.A, S-ID.A, I-C.B, SEP1-8, CC1- A-C, PS3A-, ETS1A- 2A-B, PE-12.6, 1, <b>E Anchor:</b> , 4.0, 5.0, 6.0, 7.0, , 9.0, 10.0 <b>E Pathway:</b> 0 0 0
IX.	Artificial Intelligence (AI): AI in real world	CR	LAB/CC		STANDARDS
	<ul> <li>A. Students will learn about the history and the current state of AI</li> <li>The AI timeline</li> <li>Modern AI frameworks</li> <li>B. Students will learn about the technologies powering AI</li> <li>AI hardware + software</li> <li>Machine Learning and Neural Networks (NN)</li> <li>C. Students will code and explore Neural Networks (NN)</li> <li>Coding a simple NN using Python</li> <li>Training the NN with sensor data</li> <li>Testing the NN</li> </ul>	8	18	2.0 8.0	0 0

<b>Course Title</b> Robotics and Artificial Intelligence			Course Code KT370-371			
X.	Employme	ent Portfolio	CR	LAB/CC	STANDARDS	
	<ol> <li>Portfolio</li> <li>Portfolio</li> </ol>		2	10	Academic: LS 9-10, 11-12.6 SLS 11-12.2 CTE Anchor: 2.0, 3.0 CTE Pathway: C4.0, C7.0	